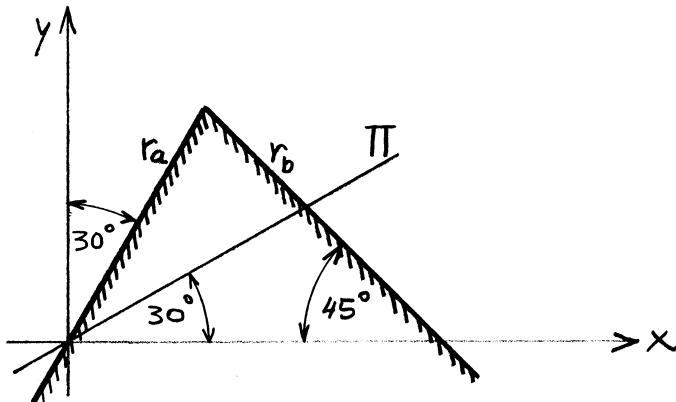


1. Na vogalu enakomerno debele homogene stene, v kateri vlada homogeno **ravninsko napetostno stanje**, izrežemo elementarni del, kakor je prikazano na skici.

Na robu  $\mathbf{r}_a$  deluje enakomerna zvezna obtežba  $\vec{p}_a = q(-\vec{\mathbf{e}}_x + \sqrt{3}\vec{\mathbf{e}}_y)$ , na robu  $\mathbf{r}_b$  pa enakomerna zvezna obtežba  $\vec{p}_b = -q\sqrt{2}(\vec{\mathbf{e}}_x + \vec{\mathbf{e}}_y)$ .

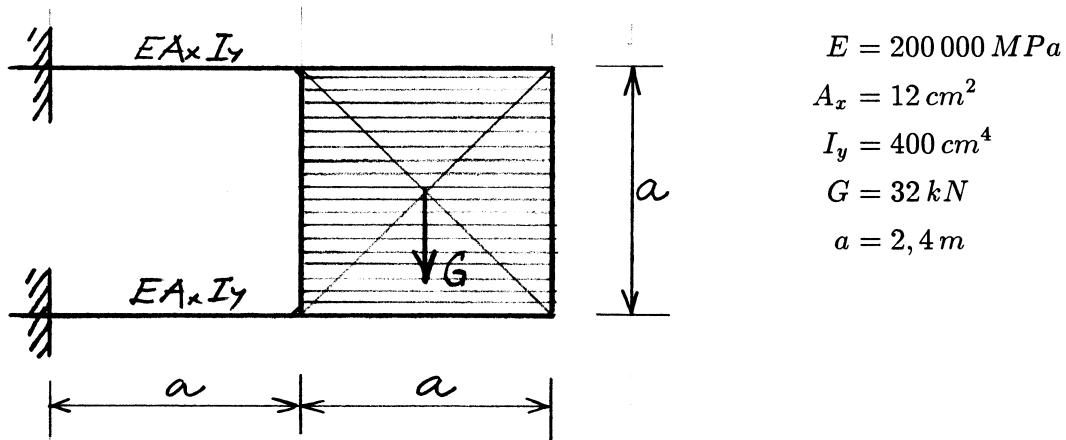
- Skiciraj obtežbo ter ustrezeni zunanji normalni robov obravnavane stene!
- Določi komponente tenzorja napetosti glede na kartezijski koordinatni sistem ( $x, y, z$ )!
- Določi rezultirajoči vektor napetosti v ravnini  $\Pi$  z njegovima komponentama v koordinatnem sistemu ( $x, y, z$ ) ter normalno in strižno napetost v tej ravnini!



2. Deformacijsko stanje nosilnega elementa v ravnini ( $x, z$ ) je opisano z matriko majhnih deformacij  $\varepsilon_{ij}$ . Točka  $T_0(0, 0)$  je nepomično vrtljivo podprta, v točki  $T_1(400, 0)$  pa je preprečen navpični pomik  $u_z$ . Določi oba pomika in zasuk točke  $T_2(200, 20)$ !

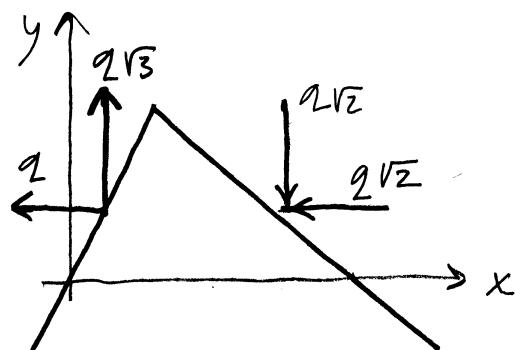
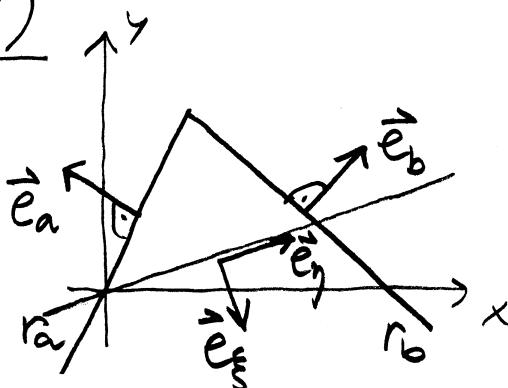
$$[\varepsilon_{ij}] = 10^{-4} \begin{bmatrix} z(2x+1) & 0 & 0,5x^2 \\ 0 & 0 & 0 \\ 0,5x^2 & 0 & 400z \end{bmatrix}$$

3. Enakomerno debela homogena plošča teže  $G$  je togo pritrjena na dva enaka previsna nosilca. Določi zasuk plošče v ravnini ( $x, z$ )!



Ad 1.)

a)



b) Rot  $r_a$ :  $\vec{e}_a = -\frac{\sqrt{3}}{2} \vec{e}_x + \frac{1}{2} \vec{e}_y$

$$\rho_{ax} = \delta_{xx} e_{ax} + \delta_{xy} e_{ay} \dots -2 = -\delta_{xx} \frac{\sqrt{3}}{2} + \delta_{xy} \cdot \frac{1}{2}$$

$$\rho_{ay} = \delta_{xy} e_{ax} + \delta_{yy} e_{ay} \dots 2\sqrt{3} = -\delta_{xy} \frac{\sqrt{3}}{2} + \delta_{yy} \cdot \frac{1}{2}$$

$$\sqrt{3} \delta_{xx} - \delta_{xy} = 2\sqrt{3} \quad \dots (A)$$

$$\delta_{yy} - \sqrt{3} \delta_{xy} = 2\sqrt{3} \quad \dots (B)$$

Rot  $r_b$ :  $\vec{e}_b = \frac{\sqrt{2}}{2} \vec{e}_x + \frac{\sqrt{2}}{2} \vec{e}_y$

$$\rho_{bx} = \delta_{xx} e_{bx} + \delta_{xy} e_{by} \dots -2\sqrt{2} = \delta_{xx} \frac{\sqrt{2}}{2} + \delta_{xy} \frac{\sqrt{2}}{2}$$

$$\rho_{by} = \delta_{xy} e_{bx} + \delta_{yy} e_{by} \dots -2\sqrt{2} = \delta_{xy} \frac{\sqrt{2}}{2} + \delta_{yy} \frac{\sqrt{2}}{2}$$

$$\delta_{xx} + \delta_{xy} = -2\sqrt{2} \rightarrow \delta_{xy} = -2\sqrt{2} - \delta_{xx}$$

$$\delta_{yy} + \delta_{xy} = -2\sqrt{2} \rightarrow \delta_{xy} = -2\sqrt{2} - \delta_{yy}$$

$$-2\sqrt{2} - \delta_{xx} = -2\sqrt{2} - \delta_{yy} \rightarrow \boxed{\delta_{xx} = \delta_{yy}}$$

(A)  $\rightarrow \sqrt{3} \delta_{xx} - (-2\sqrt{2} - \delta_{xx}) = 2\sqrt{2} \rightarrow$

$\delta_{xx} = 0$
$\delta_{yy} = 0$

$[\delta_{ij}] = 2\sqrt{2} \begin{bmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$
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(B)  $\rightarrow 2\sqrt{2}\sqrt{3} = 2\sqrt{2}\sqrt{3}$   $\swarrow$

$$c) \quad \vec{e}_\xi = \frac{1}{2} \vec{e}_x - \frac{\sqrt{3}}{2} \vec{e}_y \quad ; \quad \vec{e}_\eta = \frac{\sqrt{3}}{2} \vec{e}_x + \frac{1}{2} \vec{e}_y$$

$$\begin{pmatrix} \bar{e}_{\xi x} \\ \bar{e}_{\xi y} \\ \bar{e}_{\xi z} \end{pmatrix} = \begin{pmatrix} 0 & -2 \\ -2 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{2} \\ -\frac{\sqrt{3}}{2} \\ 0 \end{pmatrix} = \begin{pmatrix} 2\sqrt{3} \\ -2 \\ 0 \end{pmatrix}$$

$$\vec{e}_\xi = 2\sqrt{3} \vec{e}_x - 2 \vec{e}_y$$

$$\bar{e}_{\xi\xi} = \bar{e}_\xi \vec{e}_\xi$$

$$\bar{e}_{\xi\xi} = 2\sqrt{3}$$

$$\bar{e}_{\xi\eta} = \bar{e}_\xi \vec{e}_\eta$$

$$\bar{e}_{\xi\eta} = 2$$

Ad 2.)

$$\vec{\omega} = \vec{\omega}_0 + \int_{x_0}^x (\vec{\nabla} \times \vec{\epsilon}_x) dx + \int_{z_0}^z (\vec{\nabla} \times \vec{\epsilon}_z) dz$$

$$\omega_y = 0$$

$$\omega_x = \omega_z = 0$$

$$\vec{u} = \vec{u}_0 + \int_{x_0}^x (\vec{\epsilon}_x + \vec{\omega}_x) dx + \int_{z_0}^z (\vec{\epsilon}_z + \vec{\omega}_z) dz$$

$$\omega_y = \vec{\omega} \cdot \vec{e}_y = \omega_y^0 + \int_0^x \vec{e}_y (\vec{\nabla} \times \vec{\epsilon}_x) dx + \int_0^z \vec{e}_y (\vec{\nabla} \times \vec{\epsilon}_z) dz$$

$$\vec{e}_y (\vec{\nabla} \times \vec{\epsilon}_x) = \begin{vmatrix} 0 & 1 & 0 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \epsilon_{xx} & 0 & \epsilon_{xz} \end{vmatrix} = \frac{\partial \epsilon_{xx}}{\partial z} - \frac{\partial \epsilon_{xz}}{\partial x} = 10^{-4}(x+1)$$

$$\vec{e}_y (\vec{\nabla} \times \vec{\epsilon}_z) = \begin{vmatrix} 0 & 1 & 0 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \epsilon_{zx} & 0 & \epsilon_{zz} \end{vmatrix} = \frac{\partial \epsilon_{zx}}{\partial z} - \frac{\partial \epsilon_{zz}}{\partial x} = 0$$

$$\omega_y = \omega_y^0 + 10^{-4} \int_0^x (x+1) dx \rightarrow \boxed{\omega_y = \omega_y^0 + 10^{-4} \left( \frac{x^2}{2} + x \right)}$$

$$\boxed{\omega_y = \omega_{zx} = -\omega_{xz}}$$

$$u_x = u_x^0 + \int_0^x (E_{xx})_{z=0} dx + \int_0^z (E_{zx} + \omega_{zx}) dz$$

$$u_x = \int_0^z [0,5 \cdot 10^{-4} x^2 + \omega_y^0 + 10^{-4} \left( \frac{x^2}{2} + x \right)] dz$$

$$u_x = z \omega_y^0 + 10^{-4} \int_0^z (x^2 + x) dz$$

$$\boxed{u_x = z [\omega_y^0 + 10^{-4} (x^2 + x)]}$$

$$u_z = u_z^0 + \int_0^x (E_{zx} + \omega_{zx})_{z=0} dx + \int_0^z E_{zz} dz$$

$$u_z = \int_0^x [0,5 \cdot 10^{-4} x^2 - \omega_y^0 - 10^{-4} \left( \frac{x^2}{2} + x \right)] dx + \\ + \int_0^z 400 \cdot 10^{-4} z dz$$

$$\boxed{u_z = -x \omega_y^0 + 10^{-4} \left( -\frac{x^2}{2} + 200 z^2 \right)}$$

$$T_1 (x=400, z=0) \rightarrow u_z = 0$$

$$-400 \omega_y^0 - 10^{-4} \frac{400^2}{2} = 0 \rightarrow \boxed{\omega_y^0 = -200 \cdot 10^{-4}}$$

$$u_x = 10^{-4} z (x^2 + x - 200)$$

$$u_z = 10^{-4} \left( -\frac{x^2}{2} + 200x + 200z^2 \right)$$

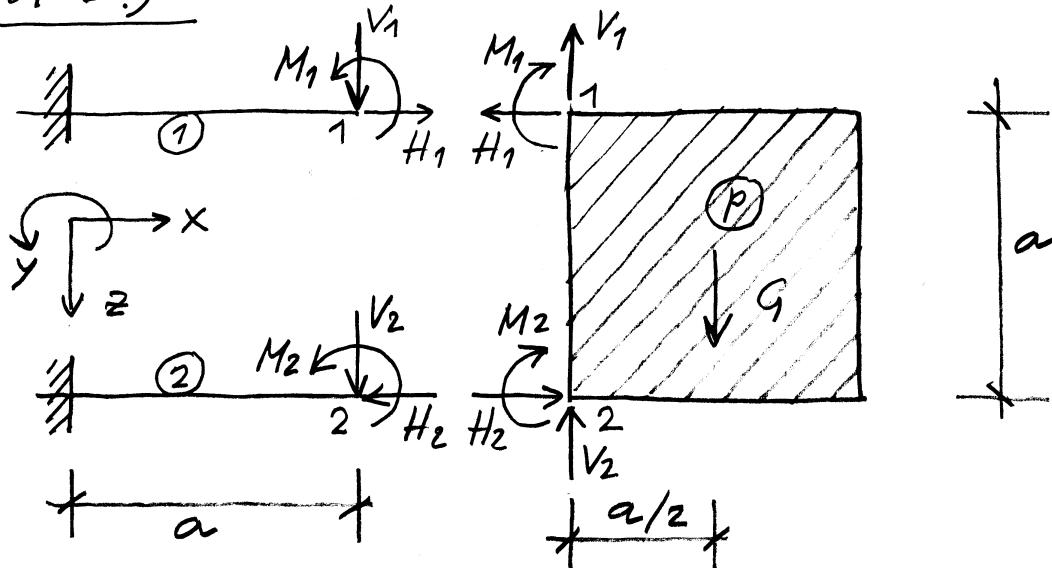
$$\omega_y = 10^{-4} \left( \frac{x^2}{2} + x - 200 \right)$$

$$T_2 (200, 20) \rightarrow$$

$u_x = 80$
$u_z = 10$
$\omega_y = 2$

$\cdot 10^{-4}$

Ad 3.)



$$(p) : \sum Z = 0 \quad \dots \boxed{V_1 + V_2 = G} \quad \dots (A)$$

$$\sum X = 0 \quad \dots \boxed{H_1 = H_2} \quad \dots (B)$$

$$\sum M^1 = 0 \quad \dots \boxed{H_2 a - M_1 - M_2 = G \frac{a}{2}} \quad \dots (C)$$

$$u_1 = H_1 \frac{a}{EA_x}$$

$$w_1 = V_1 \frac{a^3}{3EI_y} - M_1 \frac{a^2}{2EI_y}$$

$$\omega_1 = -V_1 \frac{a^2}{2EI_y} + M_1 \frac{a}{EI_y}$$

$$u_2 = -H_2 \frac{a}{EA_x}$$

$$w_2 = V_2 \frac{a^3}{3EI_y} - M_2 \frac{a^2}{2EI_y}$$

$$\omega_2 = -V_2 \frac{a^2}{2EI_y} + M_2 \frac{a}{EI_y}$$

$$\vec{u}_2 = \vec{u}_1 + \vec{\omega}_1 \times \vec{r}_2$$

$$\vec{\omega}_2 = \vec{\omega}_1 \rightarrow \boxed{\omega_2 = \omega_1} \dots (D)$$

$$\vec{u}_1 = u_1 \vec{e}_x + w_1 \vec{e}_z$$

$$\vec{\omega}_1 = \omega_1 \vec{e}_y$$

$$\vec{r}_2 = a \vec{e}_z$$

$$u_2 \vec{e}_x + w_2 \vec{e}_z = (u_1 + a \omega_1) \vec{e}_x + w_1 \vec{e}_z$$

$$\boxed{w_2 = w_1} \dots (E)$$

$$\boxed{u_2 = u_1 + a \omega_1} \dots (F)$$

$$(E) \rightarrow V_1 \frac{a^3}{3} - M_1 \frac{a^2}{2} = V_2 \frac{a^3}{3} - M_2 \frac{a^2}{2}$$

$$(D) \rightarrow V_1 \frac{a^2}{2} - M_1 a = V_2 \frac{a^2}{2} - M_2 a$$

$$\boxed{\begin{aligned} V_1 &= V_2 \\ M_1 &= M_2 \end{aligned}}$$

$$(A) \rightarrow \boxed{V_1 = V_2 = \frac{G}{2}} \quad \dots (K)$$

$$(F), (B), (K) \rightarrow -H_1 \frac{a}{EA_x} = H_1 \frac{a}{EA_x} - \frac{G}{2} \frac{a^3}{2EI_y} + M_1 \frac{a^2}{EI_y}$$

$$\boxed{H_1 \frac{2}{Ax} = G \frac{a^2}{4I_y} - M_1 \frac{a}{I_y}}$$

$$(C), (B) \rightarrow \boxed{H_1 = \frac{G}{2} + M_1 \frac{2}{a}}$$

$$\boxed{M_1 = G \frac{a(a^2Ax - 4I_y)}{4(a^2Ax + 4I_y)}}$$

$$\rightarrow \boxed{M_1 = M_2 = 1911,13 \text{ kN cm}}$$

$$\boxed{H_1 = H_2 = 31,926 \text{ kN}}$$

$$\boxed{V_1 = V_2 = 16,0 \text{ kN}}$$

$$\omega_y = \omega_1 = \omega_2 = \frac{a}{EI_y} \left( -V_1 \frac{a}{2} + M_1 \right)$$

$$\boxed{\omega_y = -2,534 \cdot 10^{-4}}$$